Application for Consent to conduct Marine Scientific Research Iceland

Date: 13th November 2020

General Information

1.1 Cruise name and/or number:	
HECLA Faroes	
1	

1.2 Sponsoring Institution(s):	
Name:	National Oceanographic Centre
Address:	European Way
	Southampton SO14 3ZH
Name of Director:	Prof. Ed Hill

1.3 Principal Investigator in charge of the Project :		
Name:	Dr. Phil Bagley	
Country:	United Kingdom	
Affiliation:	National Oceanographic Centre	
Address:	European Way	
	Southampton SO14 3ZH	
Telephone:	+44(0) 23 8059 6371	
Fax:		
Email:	phil.bagley@noc.ac.uk	
Website (for CV and photo):	https://www.noc.ac.uk/people/philba	

1.4 Entity(ies)/Participant(s) from Coastal State involved in the planning of the project:		
Name:	Andreas Macrander	
Affiliation:	Hafrannsóknastofnun / Marine and Freshwater	
	Research Institute	
Address:	Fornubúðum 5, 220 Hafnarfjörður, Ísland	
Telephone:	Sími/Tel: +354 575 2062	
	GSM: +354 865 98 49	
Fax:		
Email: andreas.macrander@hafogvatn.is		
Website (for CV and photo): www.hafogvatn.is		

2. Description of Project

2.1 Nature and objectives of the project:

HECLA is coordinated by the National Oceanography Centre (NOC) and this trial will use two submarine gliders to circumnavigate the Faroes islands to collect CTD (Conductivity, Temperature, Depth) data. The overall objective of the HECLA project is to demonstrate how near real time oceanographic data from submersible gliders can be used to feed into ocean forecasting models, and to advance near real time data gathering.

The scientific work will be undertaken in partnership with Dstl (Defence Science and Technology Laboratory), the UK Met Office, the British Oceanographic Data Centre (BODC), and the Royal Navy.

The submersible gliders will be deployed and recovered from the UK.

2.2 If designated as part of a larger scale project, then provide the name of the project and the Organisation responsible for coordinating the project:

N/A

2.3 Relevant previous or future research projects:

Following on from the successful MASSMO project where multiple Marine Autonomous Systems (MAS) demonstrated the effectiveness of MAS for offshore data collection, the HECLA project aims to build on this success to operationalise the flow of ocean data obtained from gliders into ocean forecasting models (AMM15).

One further HECLA trial is planned over the next 2 years with the aim of increasing complexity and effectiveness of offshore data gathering for the RN.

2.4 Previous publications relating to the project:

Suberg, L., **Wynn, R.B.**, van der Kooij, J., Fernand, L., Fielding, S., Guihen, D., Gillespie, D., Johnson, M., Gkikopoulou, K.C., Allan, I.J., Vrana, B., Miller, P.I., Smeed, D. and Jones, A.R. (2014) Assessing the potential of autonomous submarine gliders for ecosystem monitoring across multiple trophic levels (plankton to cetaceans) in shallow shelf seas. Methods in Oceanography, 10, 70-89.

http://projects.noc.ac.uk/massmo/

See also:

http://www.bbc.co.uk/news/science-environment-29464273

http://www.bbc.co.uk/news/uk-scotland-highlands-islands-37822097

3. Geographical Areas

3.1 Indicate geographical areas in which the project is to be conducted (with reference in Latitude and longitude, including coordinates of cruise/track/way points)

The work area we wish to work in is bounded by the box with locations A to D:

A: 57° 38.221'N; 8° 56.152'W B: 63° 25.349'N; 15° 25.704'W

C: 64° 50.771'N; 6° 44.840'W

D: 59° 55.195'N; 0° 4.065'E

However, the glider will aim to follow the general mission path described by the following waypoints:

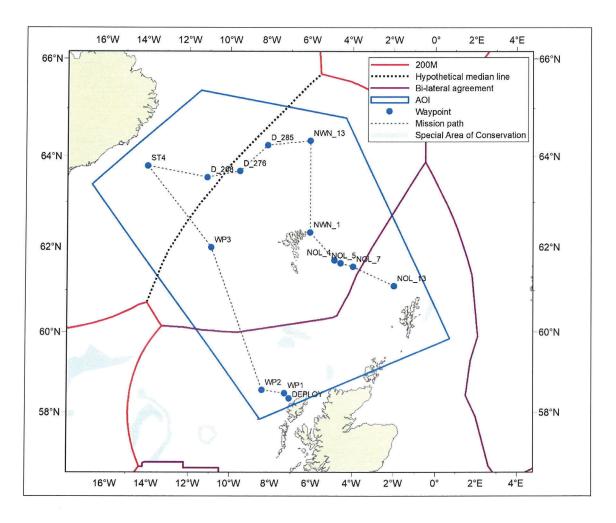
WP1: 58° 17.964'N; 7° 12.189'W WP2: 58° 35.302'N; 8° 19.213'W

WP3: 62° 2.836'N; 8° 47.810'W WP4: 63° 47.348'N; 13° 20.981'W

WP5: 64° 18.020'N; 7° 11.837'W WP6: 62° 44.231'N; 6° 38.357'W WP7: 62° 49.291'N; 4° 43.673'W

WP8: 61° 39.770'N; 4° 29.578'W WP9: 60° 35.150'N; 1° 55.516'W

3.2 Attach chart(s) at an appropriate scale (1 page, high-resolution) showing the geographical Areas of the intended work and, as far as practicable, the location and depth of sampling Stations, the tracks of survey lines, and the locations of installations and equipment. (NB: make Sure 3.1 is complete)



4. Methods and means to be used

4.1 Particulars of vessel:		
Name:	None Being Used. The intent is to launch and recover the marine autonomous platforms from Isle of Lewis and recover in the Shetland Islands	
Type/Class:		
Nationality (Flag State):		
Identification Number (IMO/Lloyds No.):		
Owner:		
Operator:		
Overall length (meters):		
Maximum draft:		
Displacement/Gross Tonnage:		
Propulsion:		
Cruising & maximum speed:		
Call sign:		
INMARSAT number and method and capability of communication (including emergency frequencies):		
Name of Master:		
Number of Crew:		
Number of Scientists on board:		

4.2 Particulars of Aircraft:	
Name:	N/A
Make/Model:	
Nationality (flag State):	
Website for diagram & Specifications:	
Owner:	
Operator:	
Overall Length (meters):	
Propulsion:	
Cruising & Maximum speed:	
Registration No.:	
Call Sign:	
Method and capability of communication	
(including emergency frequencies):	
Name of Pilot:	
Number of crew:	
Number of scientists on board:	
Details of sensor packages:	
Other relevant information:	

4.3 Particulars of Autonomous Underwater Vehicle (AUV):		
Name:	Underwater Glider	
Manufacturer and make/model:	Teledyne Webb Slocum x 2	
Nationality (Flag State):	UK	
Website for diagram & Specifications:	http://www.teledynemarine.com/slocum-	
	glider/?BrandID=23	
Owner:	Royal Navy	
Operator:	NOC	
Overall length (meters):	2.0	
Displacement/Gross tonnage:	55kg	
Cruising & Maximum speed:	0.5 knots	
Range/Endurance:	6 months	
Method and capability of communication	Iridium satellite comms, ARGOS Telesonar	
(including emergency frequencies):	modem	
Details of sensor packages:	Conductivity, temperature, depth,	
	fluorescence (Chlorophyll, backscatter,	
	CDOM)	
Other relevant information:	Depth 0-1000 m, navigation by GPS,	
	altimeter and dead reckoning. Contains	
	lithium batteries	

4.4 Particulars of Unmanned Surface Vehicles (USV):		
Name:		
Manufacturer and make/model:	N/A	
Nationality (Flag State):		
Website for diagram & Specifications:		
Owner:		
Operator:		
Overall length (meters):		
Displacement/Gross tonnage:		
Cruising & Maximum speed:		
Range/Endurance:		
Method and capability of communication		
(including emergency frequencies):		
Details of sensor packages:		
Other relevant information:		

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4.5 Particulars of Unmanned Air V	ehicles (UAV) :	
Name:		
Make/Model:	N/A	
Nationality (flag State):		
Website for diagram & Specification	ons:	
Owner:		
Operator:		
Overall Length (meters):		
Propulsion:		
Cruising & Maximum speed:		
Registration No.:		and the same of th
Call Sign:		
Method and capability of communi	action	
(including emergency frequencies) Name of Pilot:	•	
Number of crew:		- AMPANIAN
Number of scientists on board:		
Details of sensor packages:		
Other relevant information:		
4.6 other craft in the project, include	ling its use:	
NONE		
4.7 Particulars of methods and scient	entific instruments:	
Types of samples and	Methods to be used:	Instruments to be used:
Measurements:	Wellious to be used.	motiuments to be doca.
	Continuous massurament	Continuously recording
Temperature, salinity, and	Continuous measurement	Continuously recording
fluorescence	from sensors mounted on the	conductivity, temperature
	surface and submarine	depth probe (CTD) and
	gliders	fluorescence sensors
4.8 Indicate nature and quantity of	substances to be released into the	marine environment:
N/A		
1477		
4.9 Indicate whether drilling will be	carried out. If yes, please specify:	
No	carried out. If yes, please specify.	
NO		
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4.9.1 Indicate whether explosives v		voe and trade name.
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7. Port Calls

7.1 Dates and Names of intended ports of call:
N/A
7.2 Any special logistical requirements at ports of call:
N/A
7.3 Name/Address/Telephone of shipping agent (if available):
N/A

8. Participation of the representative of the Coastal State

8.1 Modalities of the participation of the representative of the Coastal State in the research		
	Project:	
	N/A	

8.2 Proposed dates and ports for embarkation/disembarkation:
N/A

9. Access to Data, Samples and Research Results

9.1 Expected dates of submission to Coastal State of preliminary report, which should include The expected dates of submission of the data and research results:

30 Jan 2022

- 9.2 Anticipated dates of submission to the Coastal State of the final report (This must be within 1 year of completion of the cruise)31 March 2022
- 9.3 Proposed means for access by Coastal State to data (including formal) and samples as per BODC Weblink: https://www.bodc.ac.uk/resources/inventories/cruiseinventory/search/

All HECLA raw and calibrated data will be accessible from the British Oceanographic Data Centre (BODC)

9.4 Proposed means to provide Coastal State with assessment of data, samples and Research results:

In addition to data being held at BODC (see above), results will be published in scientific papers/reports and presented at national and international for a

9.5 Proposed means to provide assistance in assessment or interpretation of data, samples And research results:

In addition to data being held at BODC (see above), results will be published in scientific papers/reports and presented at national and international fora

9.6 Proposed means of making results internationally available (to obtain cruise reports these Can be obtained via the BODC weblink see below:

In addition to data being held at BODC (see above), results will be published in scientific papers/reports and presented at national and international fora

10. Other permits Submitted

10.1 Indicate other types of Coastal State permits anticipated for this research (received or	
Pending):	
N/A	

11. List of Supporting Documentation

11.1 List of attachments, such as additional forms required by the Coastal State, etc.:	
N/A	

Signature:

Contact information of the focal point: See Section 1.3 above

Name: Country: Affiliation: Address: Telephone: Email:

UPLOAD YOUR FINAL CRUISE REPORT: https://www.bodc.ac.uk/resources/inventories/cruise inventory/search/

SEND YOUR FINAL CRUISE REPORT: <u>msrapplications@fco.gov.uk</u>